

# Force-Couple System

Steven Vukazich

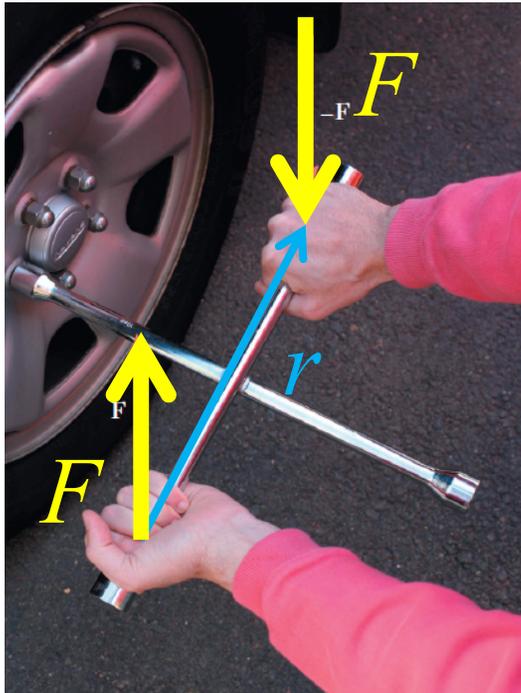
San Jose State University

## Moment of A Force About a Point



In order to analyze structures subjected to general force systems that can cause rotation, we introduced the concept of the moment of a force about a point

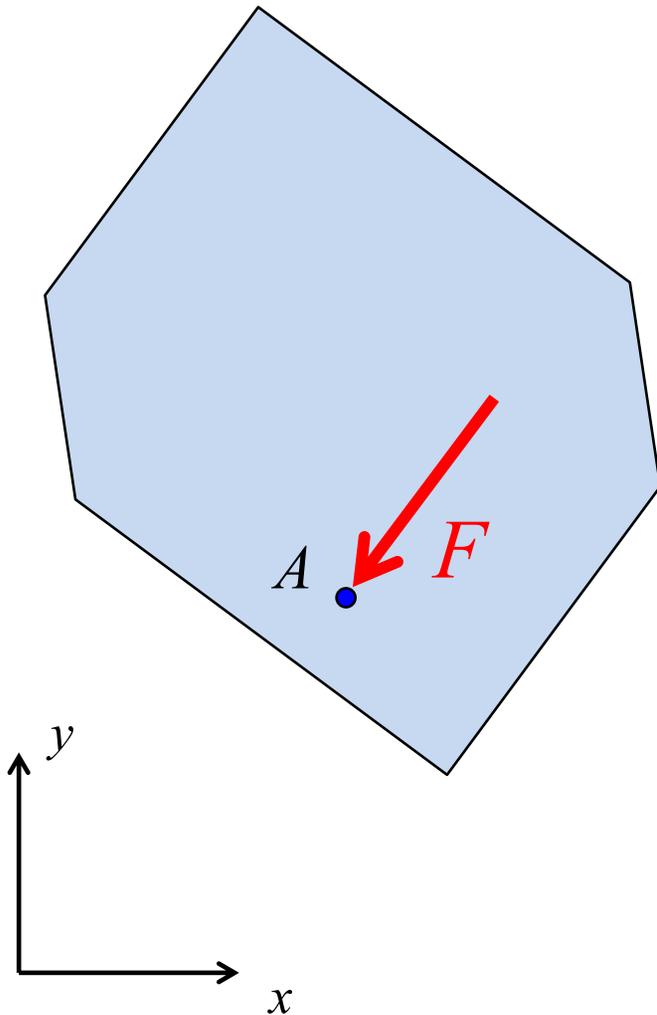
## Moment of a Couple



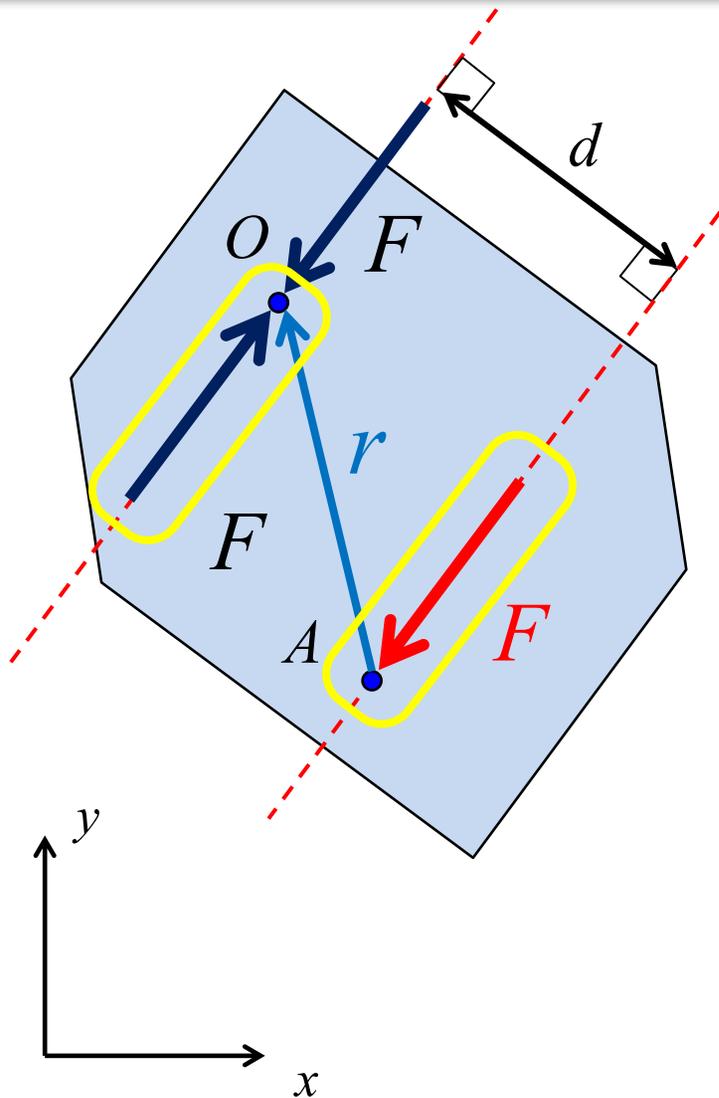
We then added the related concept of the moment of a couple

We are now ready to understand one of the fundamental concepts for the analysis of bodies subjected to general force systems – **the force-couple system**

**Consider a force acting on a  
Planar Body at Point A**



**At Point  $O$ , add Two Forces With the Same Magnitude, Same Line of Action, and Opposite Sense**

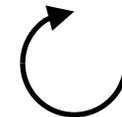


The net effect of the forces at point  $O$  on the body is zero

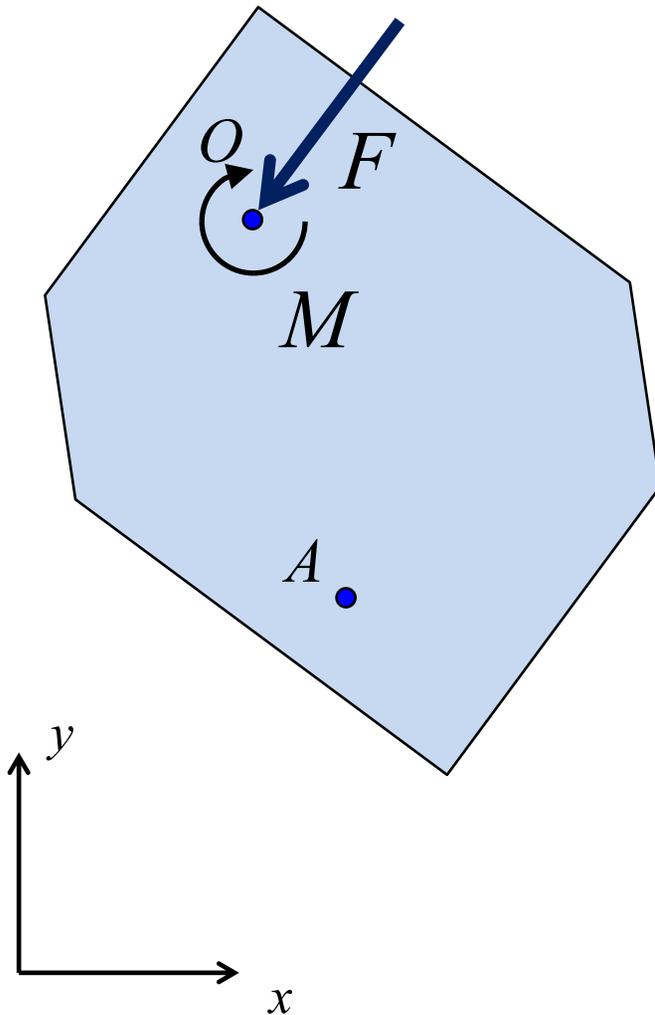
The two forces outlined in yellow form a couple

$$\mathbf{M} = \mathbf{r} \times \mathbf{F}$$

$$M = dF$$



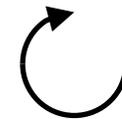
## Equivalent Force-Couple System



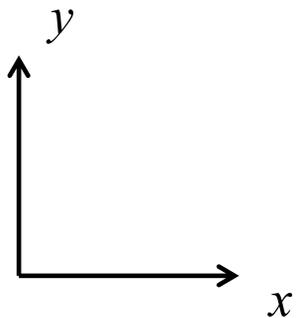
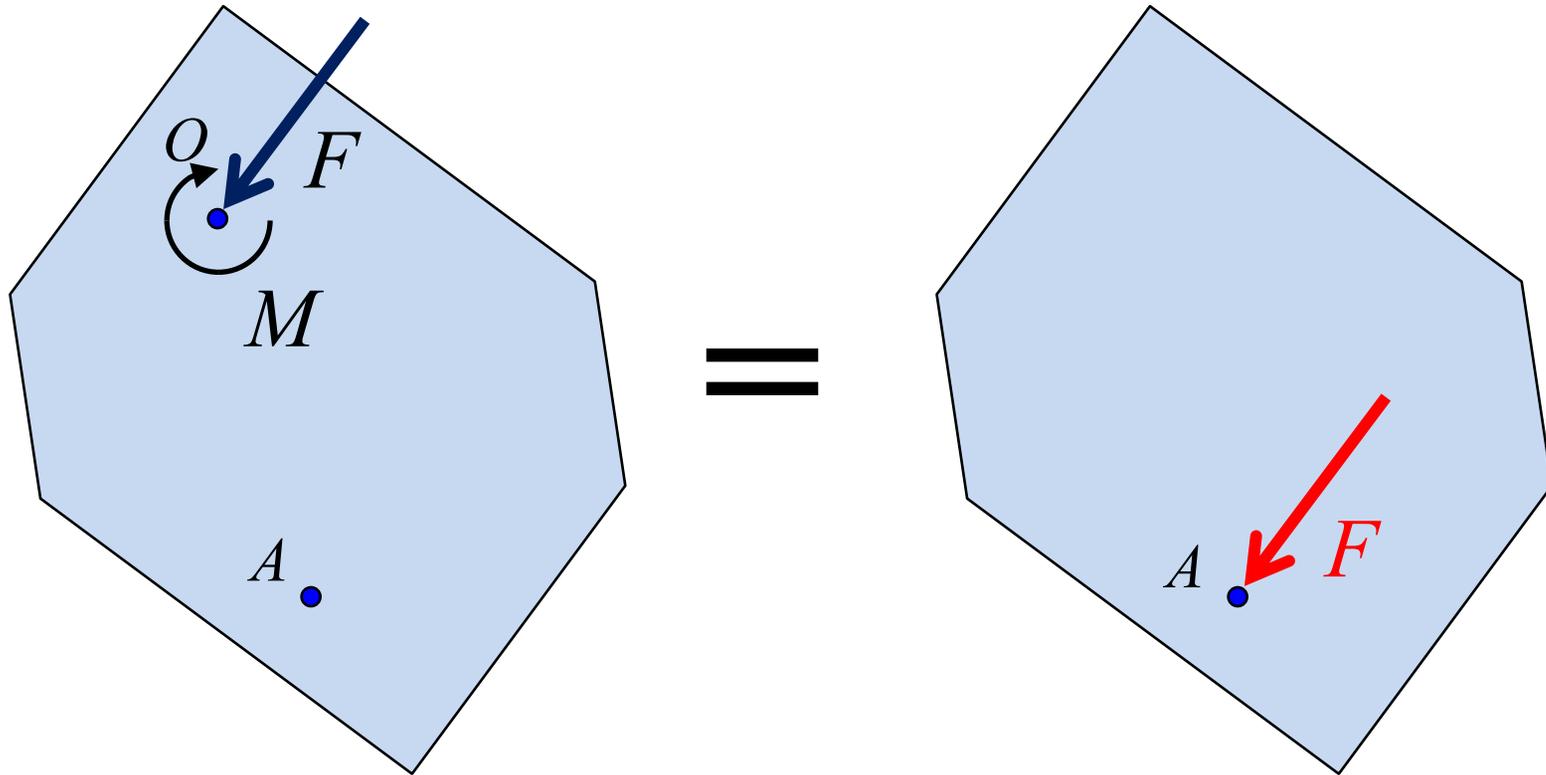
The force-couple system at point  $O$  has same effect on the body as the force applied at  $A$ !

$$\mathbf{M} = \mathbf{r} \times \mathbf{F}$$

$$M = dF$$



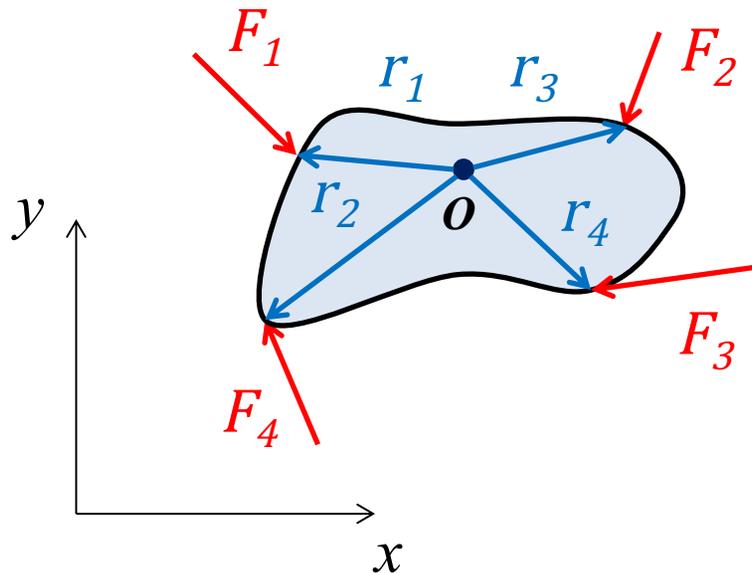
## Equivalent Force-Couple System



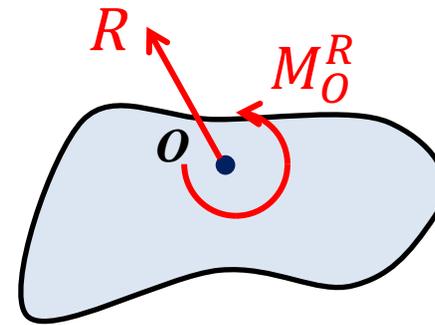
Note that the couple in the force-couple system is equal to the moment of the force  $F$  about point  $O$

# Any Force System Acting on a Rigid Body can be Replaced by a Resultant Force-Couple System at Any Point

## Planar Force System



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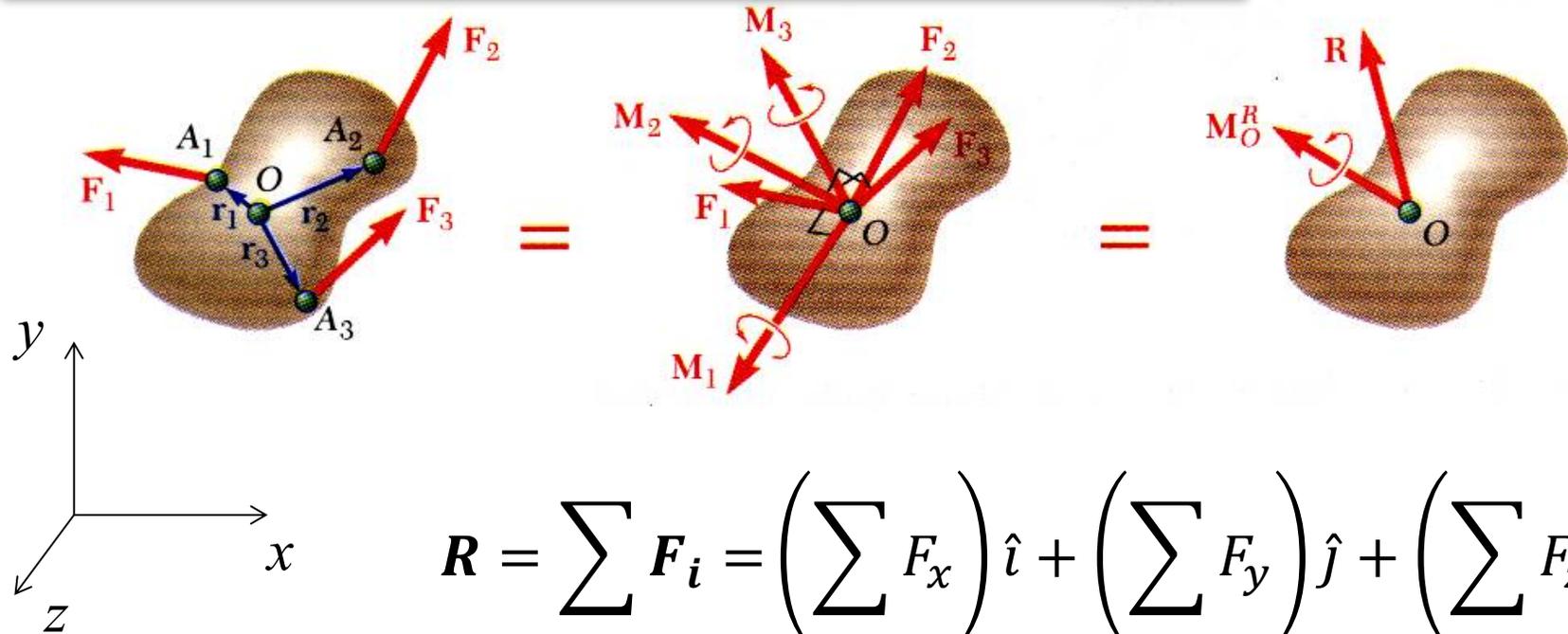
$$\mathbf{R} = \sum \mathbf{F}_i = \left( \sum F_x \right) \hat{i} + \left( \sum F_y \right) \hat{j}$$

$$\mathbf{M}_O^R = \sum (\mathbf{r}_i \times \mathbf{F}_i)$$

Note that the resultant force is always the same but the resultant couple depends on the location of the point

# Any Force System Acting on a Rigid Body can be Replaced by a Resultant Force-Couple System at Any Point

## General Three-Dimensional Force System



$$\mathbf{R} = \sum \mathbf{F}_i = \left( \sum F_x \right) \hat{i} + \left( \sum F_y \right) \hat{j} + \left( \sum F_z \right) \hat{k}$$

$$\mathbf{M}_O^R = \sum (\mathbf{r}_i \times \mathbf{F}_i)$$